



# mARZ Sat

An Arizona Space Grant  
Consortium Program

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# Program Goals

- Develop a top-level design for a student built Mars microsatellite
- Build a geographically disparate team
  - Arizona State University
  - Embry-Riddle Aeronautical University
  - Northern Arizona University
  - University of Arizona
- Student education

# Geographically Disparate, Or: How I learned to stop worrying and love the telecon

- Inter & Intra team communication a top priority from the start
  - weekly program telecons
  - weekly management telecons
  - monthly all-hands meetings
  - weekly to daily subsystem telecons & meetings

# Geographically Disparate con't

- Design practices adopted
  - Well defined communication channels and flow of information
  - Frequent reviews
  - Tight interface specifications
  - Rigorous documentation requirements and configuration management procedures
  - Use of a central file server
  - Use of mailing lists

# mARZ Sat Mission

- Capture high resolution images of a set of predefined activities performed by Telesat
- Transfer those images back to Earth via Telesat

# Program Requirements

- Budget not to exceed 20M FY'03 dollars
- 2008 delivery
- 20kg mass and a target volume of 8 L.
- Launch, transit, & insertion attached to Telesat
- After release, autonomously maintain station near Telesat for 3 months
- Capture images of all scheduled imaging events and relay images back to Telesat when scheduled

# mARZSat Subsystems

- Attitude, Orbit, Determination, and Control (AODC)
- Structures, Mechanisms, Thermal, and Radiation (SMTR)
- Payload (PAY)
- Command and Data Handling (C&DH)
- Electrical and Power Systems (EPS)
- Communication (COMM)

# Goals for Subsystems

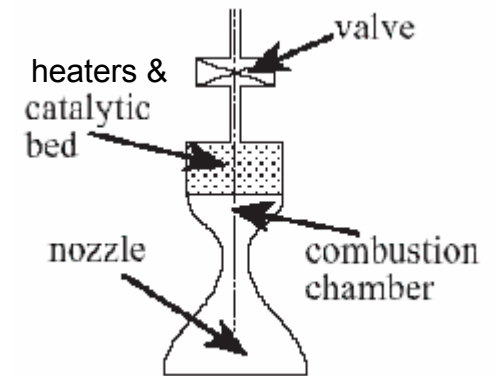
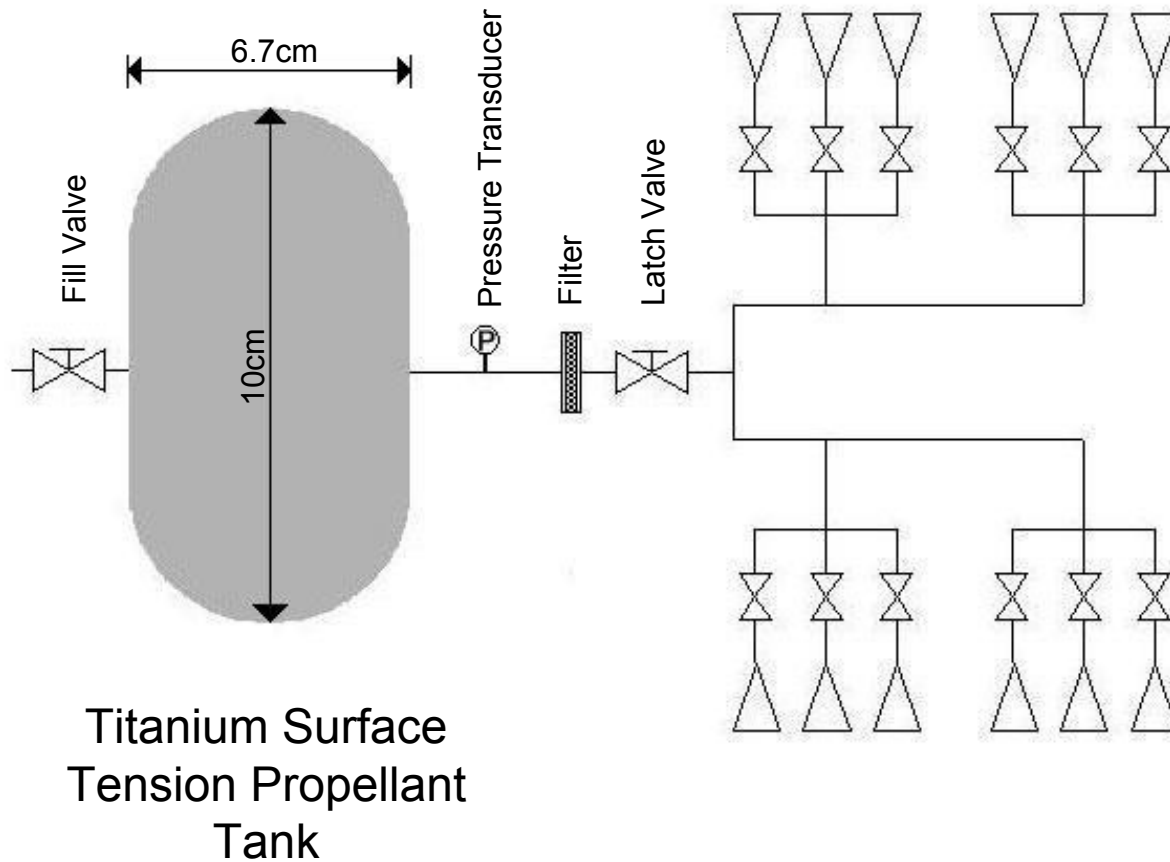
- Emphasis on Trades
  - Trade Drivers
- Utilizing micro-technology
  - Technology Readiness Levels (TRL)
- Interaction with industry
  - NASA Jet Propulsion Laboratory
  - Spectrum Astro



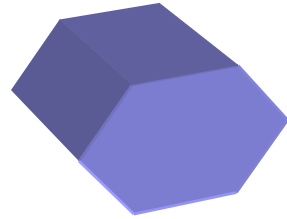
# Examples of Trades and Design Work

	Pro's	Con's
Passive	<ul style="list-style-type: none"> <li>▪ simple</li> <li>▪ minimal requirements</li> </ul>	<ul style="list-style-type: none"> <li>▪ not capable of 1° accuracy</li> </ul>
Pure Spin Stabilization	<ul style="list-style-type: none"> <li>▪ resists disturbance torques</li> <li>▪ &lt;1° accuracy</li> </ul>	<ul style="list-style-type: none"> <li>▪ more propellant to reorient</li> <li>▪ precession and wobble</li> </ul>
Dual Spin Stabilization	<ul style="list-style-type: none"> <li>▪ resists disturbance torques</li> <li>▪ &lt;1° accuracy,</li> <li>▪ camera is not rotating</li> </ul>	<ul style="list-style-type: none"> <li>▪ same as above</li> <li>▪ bearings on de-spun section may fail</li> </ul>
Reaction Wheels	<ul style="list-style-type: none"> <li>▪ &lt;1° accuracy</li> <li>▪ minimal propellant</li> </ul>	<ul style="list-style-type: none"> <li>▪ large volume, mass, and power requirements</li> </ul>
<b>Three-Axis Stabilization</b>	<ul style="list-style-type: none"> <li>▪ <b>easily maneuverable</b></li> <li>▪ <b>&lt;1° accuracy</b></li> </ul>	<ul style="list-style-type: none"> <li>▪ <b>propellant limits mission duration</b></li> </ul>

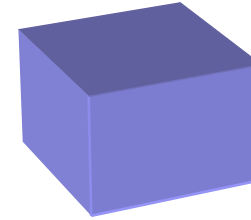
# Examples of Trades and Design Work



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2607cm<sup>3</sup>



3602 cm<sup>3</sup>

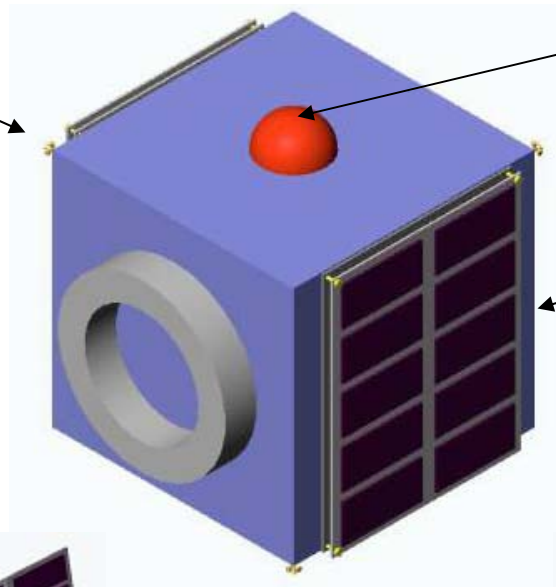
Material: Aluminum 6061-T6

	Pro	Con
Aluminum 6061-T6	Inexpensive High Availability Moderate Temperature Range Easily Machined	Lower Strength High Density Low Melting Point
Titanium	High Temperature Range High Strength Low Density High Melting Point	Hard to Machine Expensive Less available

# Examples of Trades and Design Work

Micro Thrusters

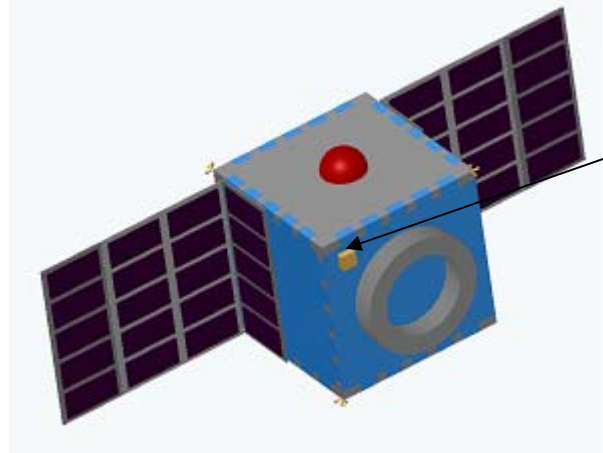
**Launch configuration:**



Antenni

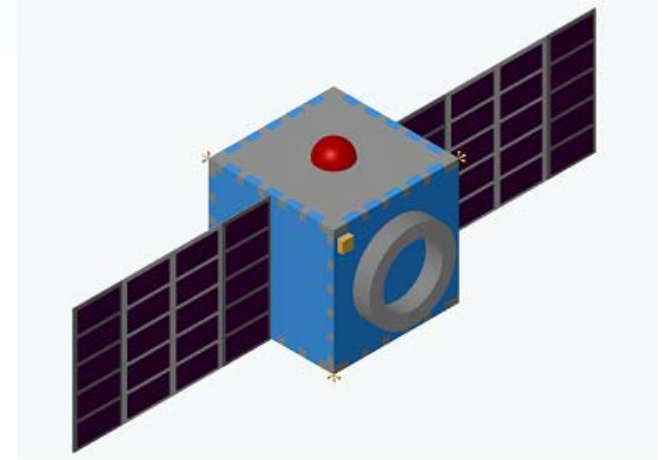
Solar Panels (2)

**Mid-Deploy configuration:**

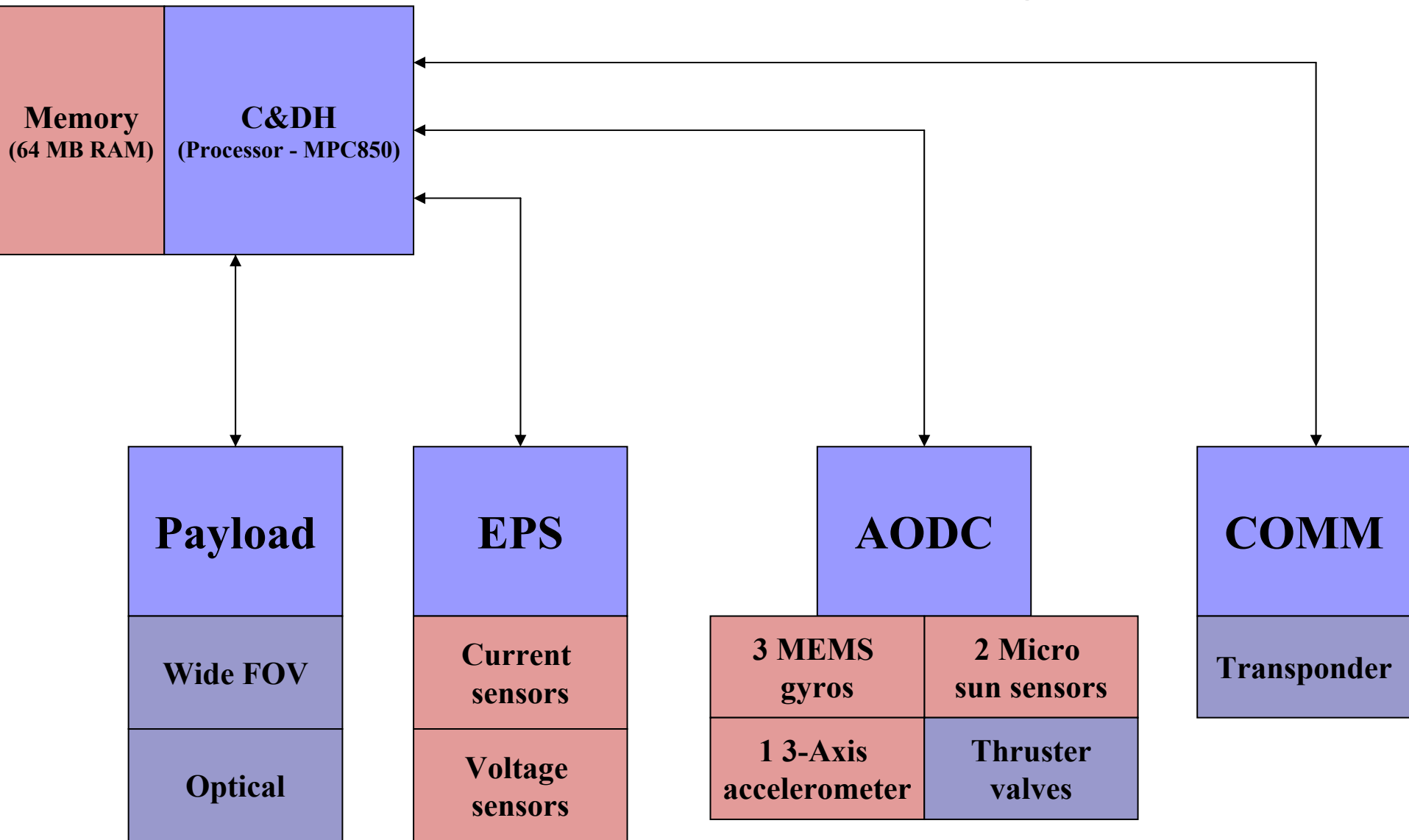


Sun  
Sensor

**Deployed configuration:**

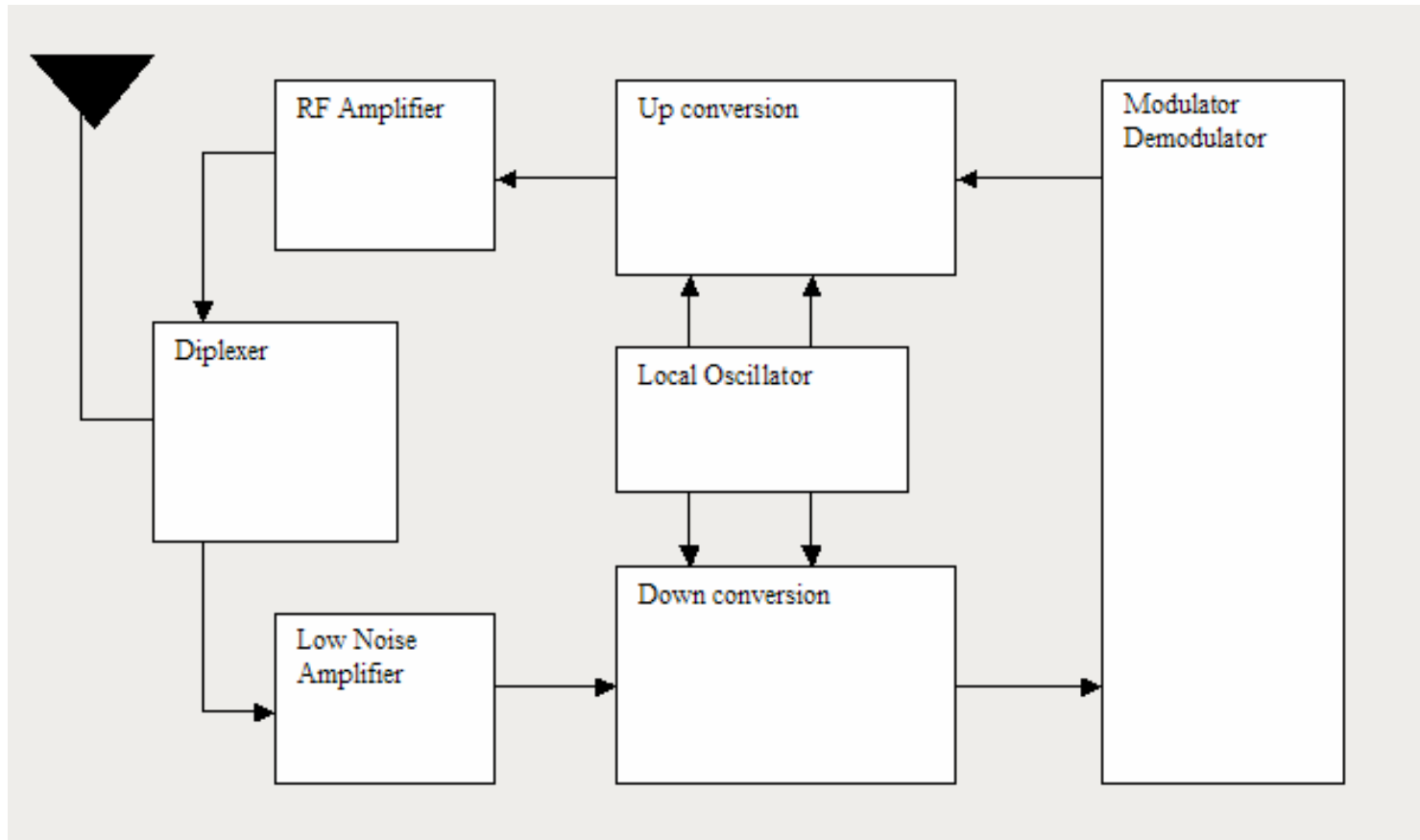


# Examples of Trades and Design Work

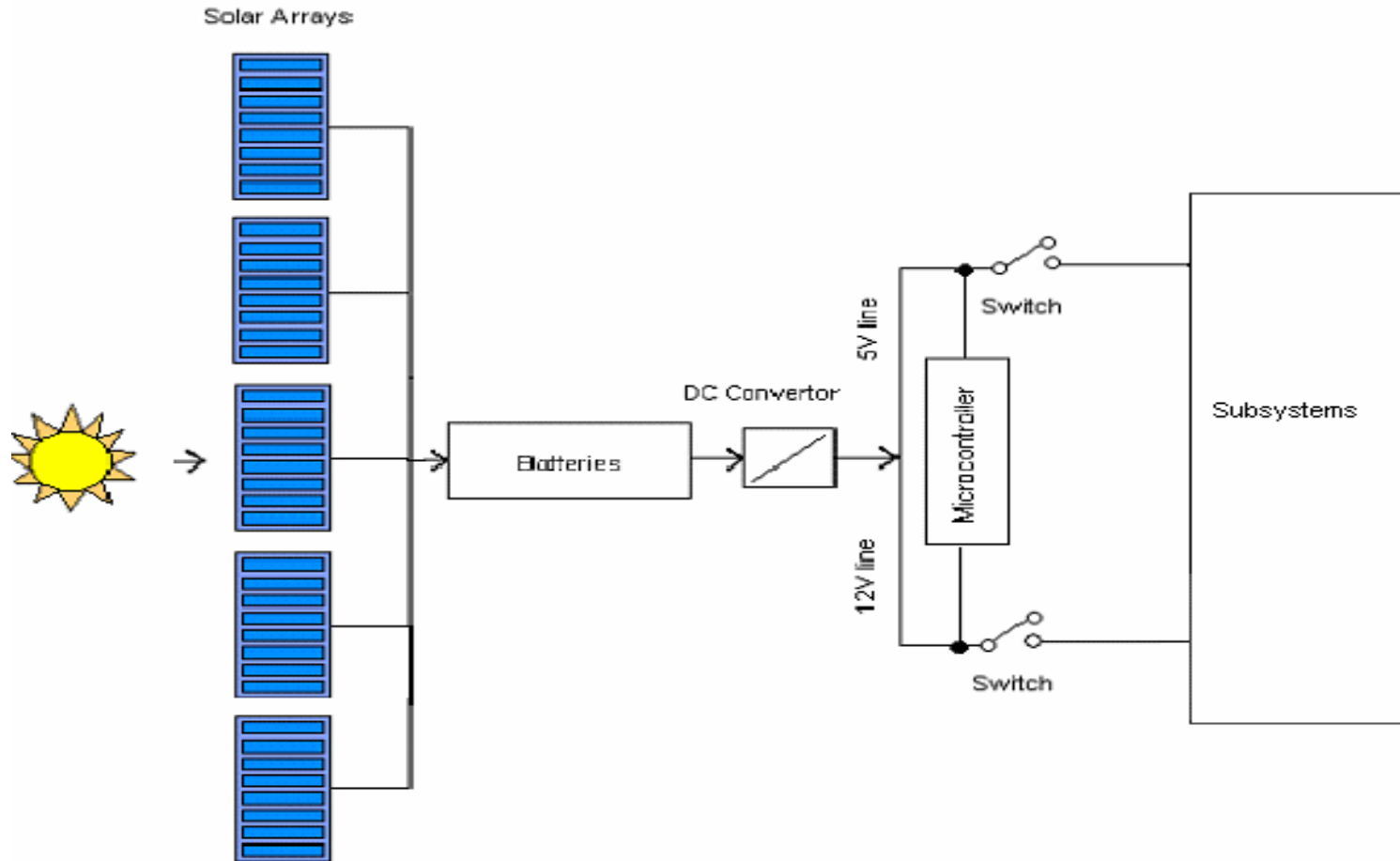


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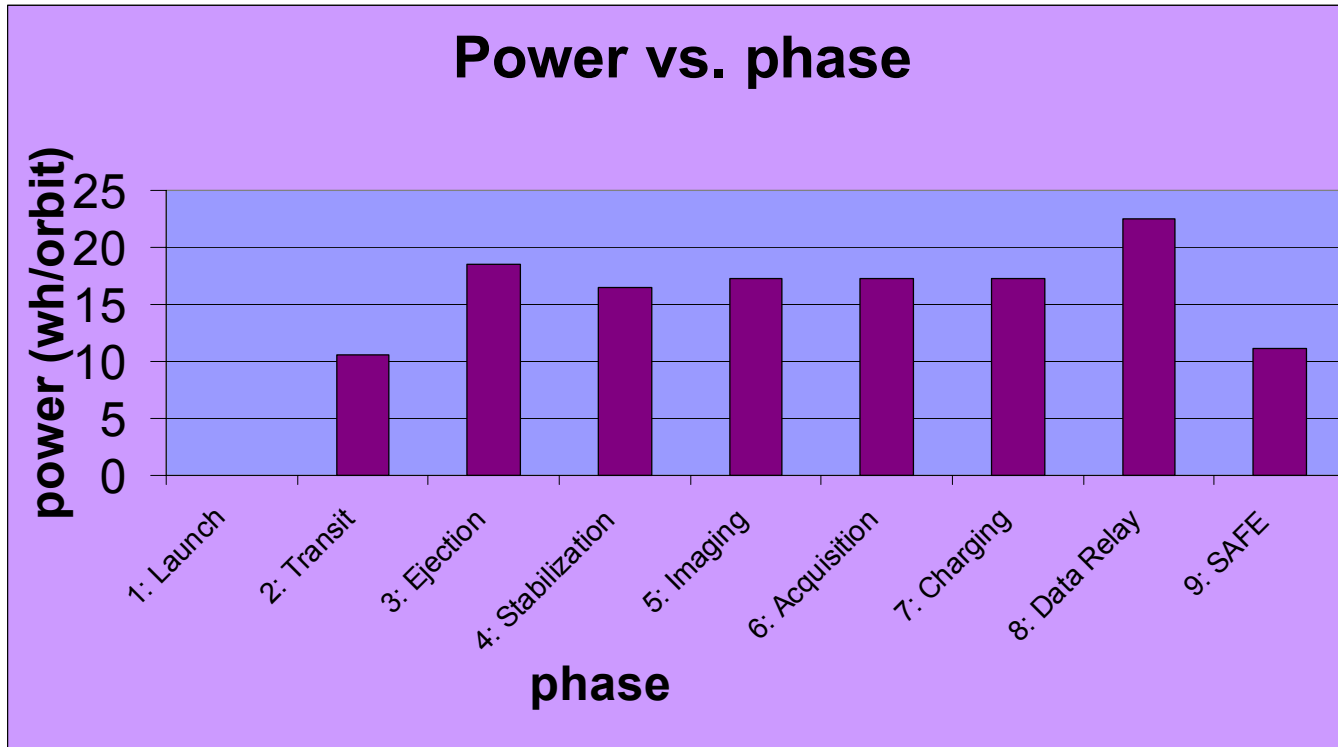
## Block Diagram



# Examples of Trades and Design Work



# Examples of Trades and Design Work



Phase	Power
1: Launch	0.00
2: Transit	10.52
3: Ejection	18.57
4: Stabilization	16.52
5: Imaging	17.28
6: Acquisition	17.29
7: Charging	17.28
8: Data Relay	22.53
9: SAFE	11.13

- Maximum power consumption occurs in the eighth phase which is the data relay phase.

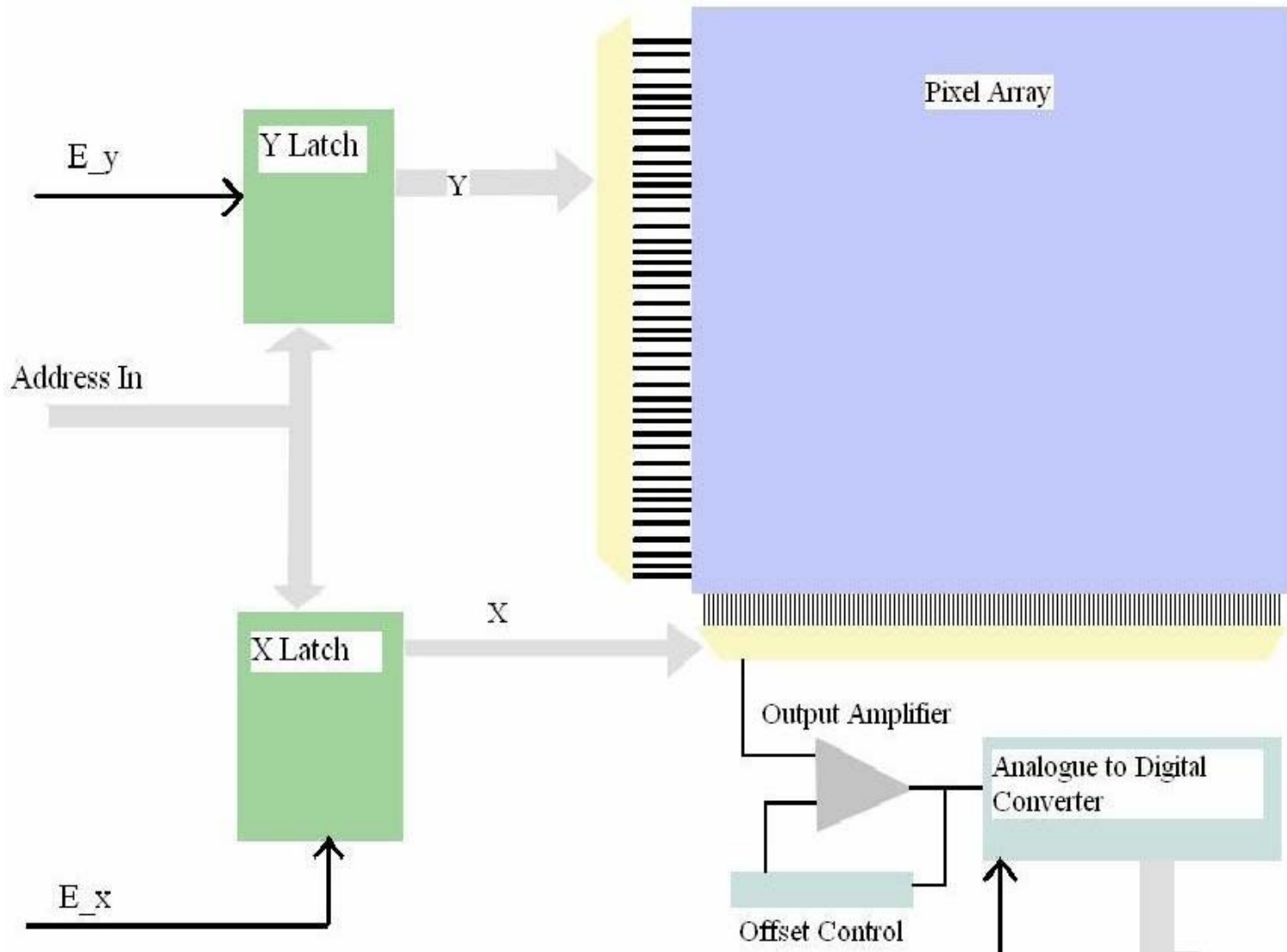


# Examples of Trades and Design Work

- F-number: 1.4
  - Constrained by VMS (Visual Monitoring System) document
- Full field-of-view: 30 degrees
- Focal Length: 2.87 cm
- Aperture Diameter: 2.052cm
- Accuracy of 200 arc seconds
- 500 star catalog



# Examples of Trades and Design Work



# Lessons Learned

- It is possible to have a successful multi-institutional collaborative design project.
- A large database of Martian information was collected and a greater understanding of Martian missions was attained.
- Ability to apply mARZSat concept study to other missions.